

(1)

$$G_{BWP} = A_0 f_0$$

$$A(s) = \frac{A_0}{1 + sT_0}$$

$$f_0 = \frac{1}{2\pi T_0}$$

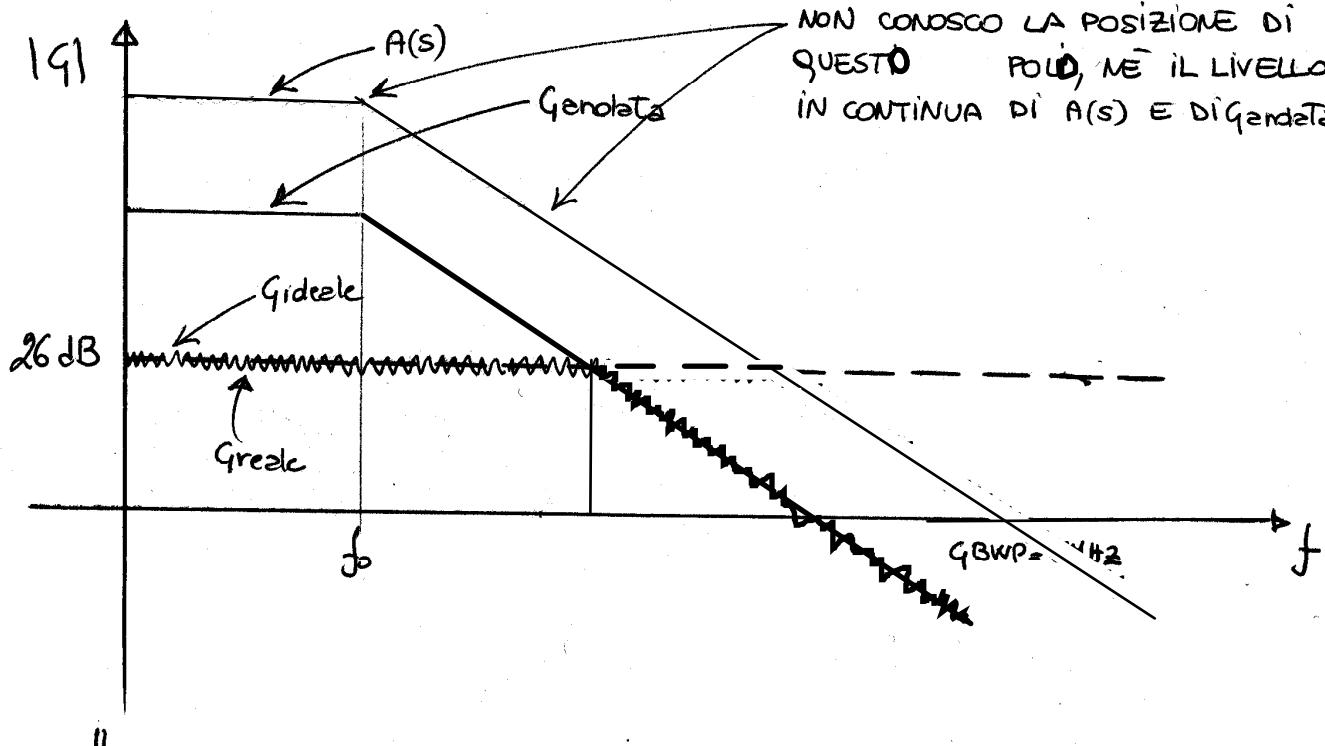
$$G_{id} = - \frac{R_2}{R_1} = - \frac{100 \text{ k}\Omega}{5 \text{ k}\Omega} = -20$$

$$G_{loop}(s) = - \frac{R_1}{R_1 + R_2} \quad A(s) = - \frac{R_1}{R_1 + R_2} \frac{A_0}{1 + sT_0}$$

↓

$$G_{endata} = - G_{id} \cdot G_{loop} = + \frac{R_2}{R_1} \cdot \frac{R_1}{R_1 + R_2} \frac{A_0}{1 + sT_0} = \frac{R_2}{R_1 + R_2} \cdot \frac{A_0}{1 + sT_0}$$

↳ PROCEDIAMO PER VIA GRAFICA; NOTARE CHE NON È NECESSARIO CONOSCERE A_0 e f_0 INDIPENDENTEMENTE MA CI È QUI SUFFICIENTE CONOSCERE IL PRODOTTO GUADAGNO - LARGHEZZA DI BANDA DELL'OPERAZIONALE



↓
Guadagno in continua: $G(0) = -20 \Rightarrow |G(0)|_{dB} = 26dB$

Banda passante: $f_{BP} = \frac{G_{BWP}}{G(0)} \frac{R_1}{R_1 + R_2} = 11.9 \text{ kHz}$

(2)

$$\varepsilon = \left| \frac{1}{G_{\text{loop}}(0)} \right|$$

$$G_{\text{loop}}(0) = -A_0 \cdot \frac{R_1}{R_1 + R_2}$$

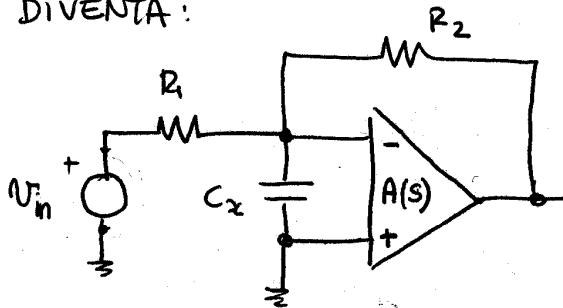
↓

$$\varepsilon = 1\% \Leftrightarrow \frac{R_1 + R_2}{R_1} \cdot \frac{1}{A_0} = 10^{-3} \Rightarrow A_0 = \frac{R_1 + R_2}{R_1} \cdot 10^3 = 2 \cdot 10^4$$

$$Q_{\text{BWP}} = A_0 f_{PD} \rightarrow \text{PER AVERE } Q_{\text{BWP}} = 5 \text{ MHz} \rightarrow f_{PD} = \frac{Q_{\text{BWP}}}{A_0} = \frac{5 \text{ MHz}}{2 \cdot 10^4} \approx 24 \text{ Hz}$$

(3) PER AVERE MARGINE DI TASE 45° , IL SECONDO POLO DEL GUADAGNO D'ANELLO DEVE CADERE ALLA FREQUENZA A CUI $G_{\text{loop}} = 0 \text{ dB}$.

SE INSERIAMO UNA CAPACITÀ C_x TRA I MORSETTI IL CIRCUITO DIVENTA:

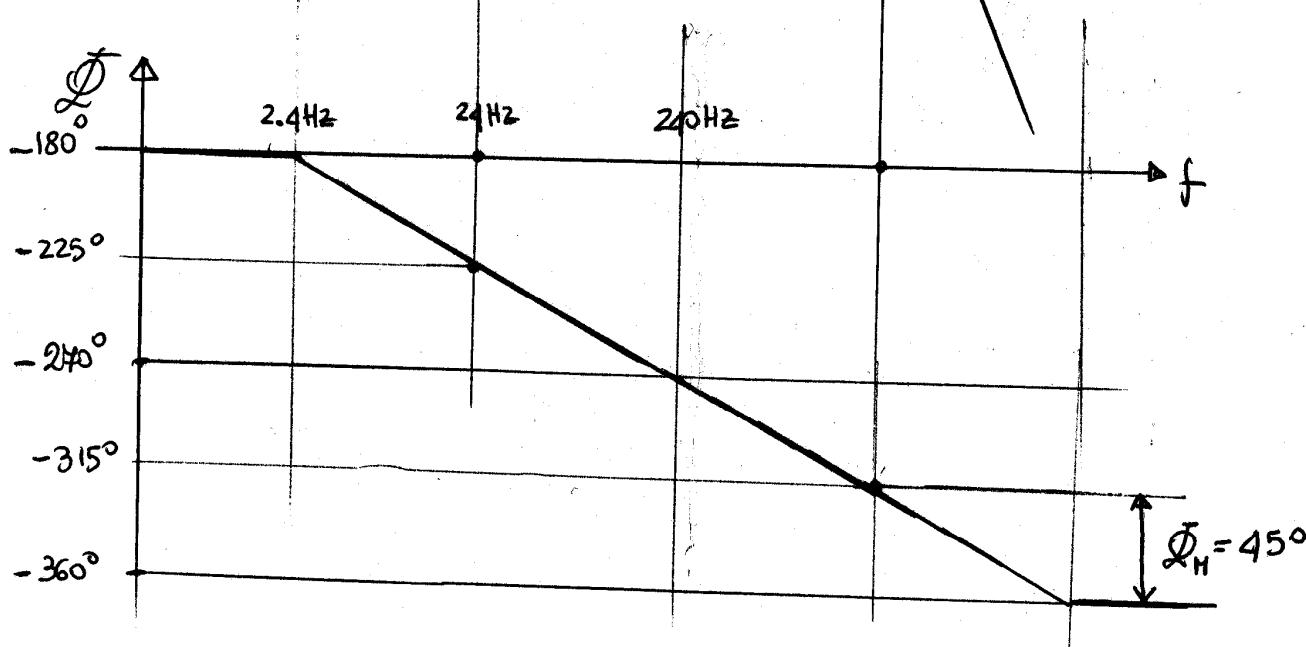
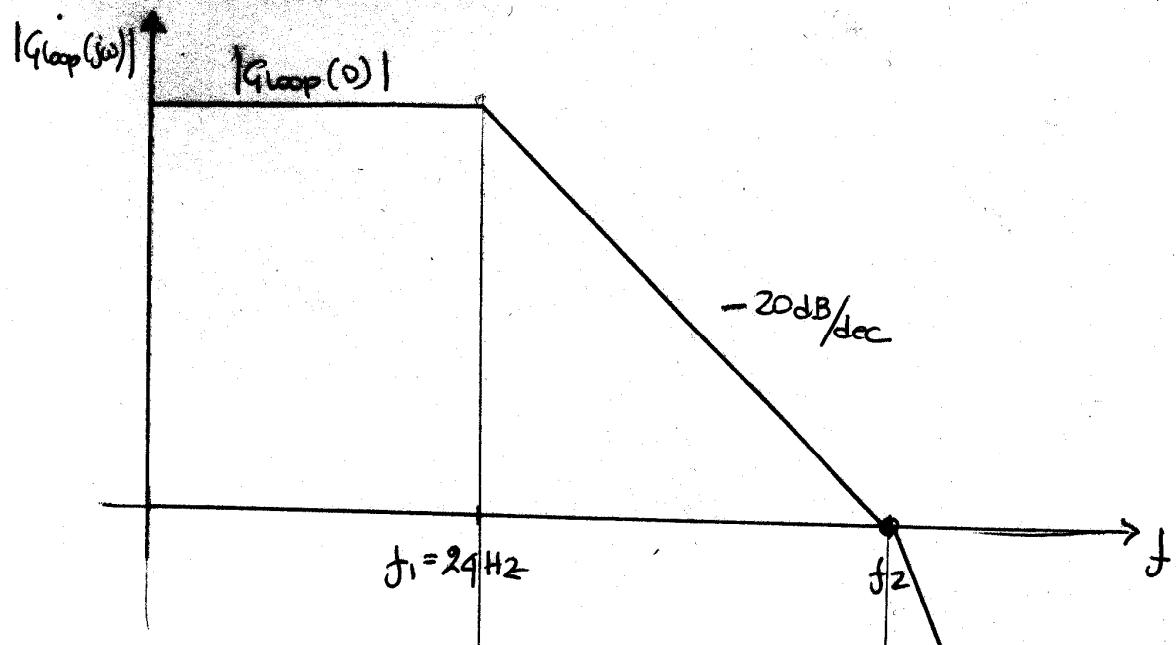


$$G_{\text{loop}}(s) = G_{\text{loop}}(0) \cdot \frac{1}{(1+s\tau_1)(1+s\tau_2)}$$

$$G_{\text{loop}}(0) = -\frac{R_1}{R_1 + R_2} \cdot A_0 = -\frac{5 \text{ k}\Omega}{5 \text{ k}\Omega + 100 \text{ k}\Omega} \cdot 2 \cdot 10^4 = -40^3$$

$$\tau_1 = \frac{1}{2\pi f_{PD}} = 6.63 \text{ ms}$$

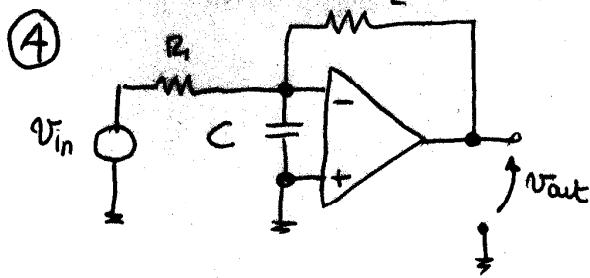
$$\tau_2 = C_x (R_1 \parallel R_2)$$



$$f_2 = |G_{\text{loop}}(0)| \times f_1 = 1000 \times 24 \text{ Hz} = 2.4 \text{ kHz}$$

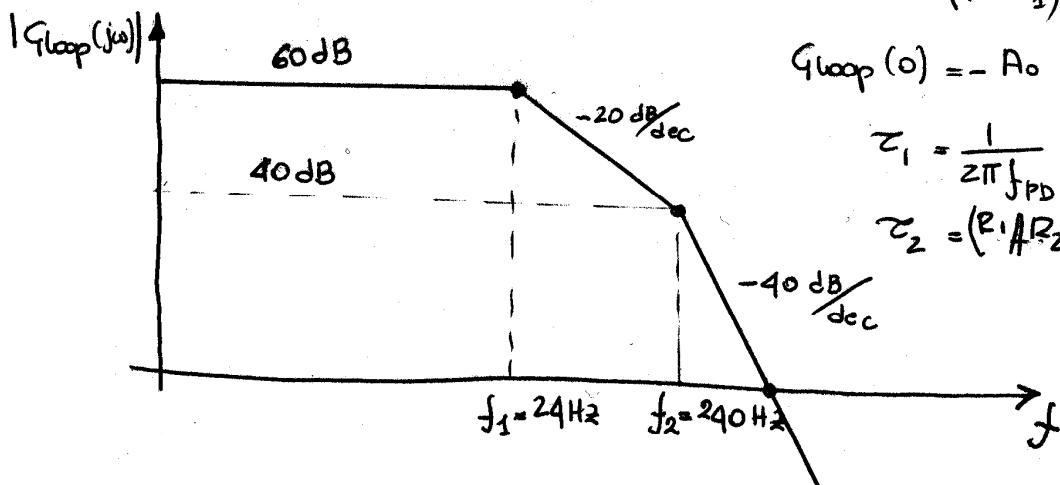
$$f_2 = \frac{1}{2\pi C_x} = \frac{1}{2\pi C_x (R_1 \parallel R_2)} \rightarrow C_x = \frac{1}{2\pi f_2 (R_1 \parallel R_2)} = 14 \text{ mF}$$

$$\hookrightarrow C_x \leq 14 \text{ mF}$$



$$C = 10 C_{MAX} = 140 \text{ mF}$$

$$G_{loop}(s) = G_{loop}(0) \frac{1}{(1+s\tau_1)(1+s\tau_2)}$$



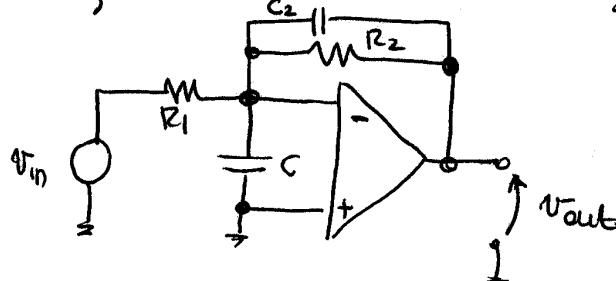
$$G_{loop}(0) = -A_0 \frac{R_1}{R_1 + R_2} = -10^3$$

$$\tau_1 = \frac{1}{2\pi f_{PD}} = 6.65 \text{ ms}$$

$$\tau_2 = (R_1 || R_2) \cdot C = 0.667 \mu\text{s}$$

IL $|G_{loop}|$ TAGLIA L'ASSE 0dB CON PENDENZA -40 dB/dec . PER RENDERE IL CIRCUITO STABILE, IL $|G_{loop}|$ DEVE TAGLIARE L'ASSE 0dB CON PENDENZA -20 dB/dec .

PONENDO LA CAPACITÀ C IN PARALLELO ALLA RESISTENZA R_2 , INTRODUCIAMO UNO ZERO CON COSTANTE DI TEMPO τ_2 E MODIFICHIAMO LA FREQUENZA DEL POLO A FREQUENZA f_2 .



$$\tau_2 = C_2 R_2$$

$$\tau_2^* = (C + C_2)(R_1 || R_2)$$

\downarrow
PONIAMO LO ZERO A FREQUENZA PARI A $f_2 \Rightarrow \frac{C_2 R_2}{f_2} = C \frac{R_1 R_2}{R_1 + R_2}$
 $\hookrightarrow C_2 = C \frac{R_1}{R_1 + R_2} = 6.7 \text{ mF}$

IL POLO SI PORTERA` A FREQUENZA $f_2^* = \frac{1}{2\pi(C + C_2)(R_1 || R_2)} = 228 \text{ Hz}$

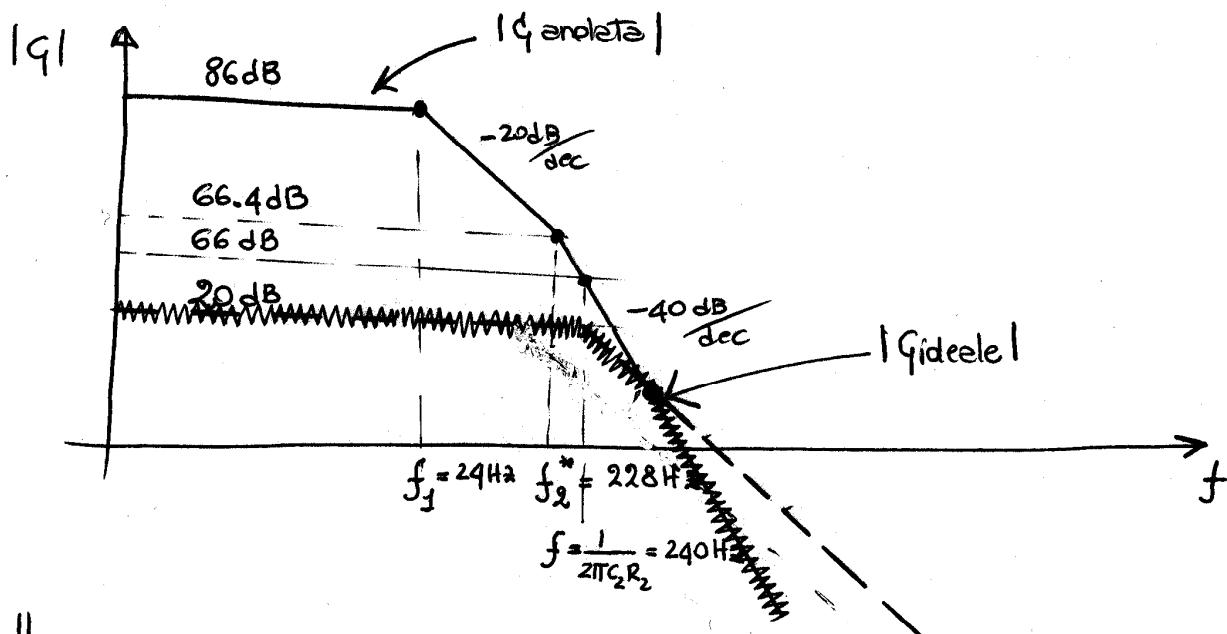
CALCOLIAMO LA BANDA DEL CIRCUITO COSÌ MODIFICATO:

$$G_{\text{andata}} = - G_{\text{id}} \cdot G_{\text{loop}}$$

$$G_{\text{id}}(s) = - \frac{R_2}{R_1} \frac{1}{1 + sC_2 R_2}$$

$$G_{\text{loop}}(s) = - G_{\text{loop}}(0) \frac{1 + sT_2}{(1 + sT_1)(1 + sT_2^*)}$$

$$G_{\text{andata}} = - \frac{R_2}{R_1} \cdot \frac{1}{1 + sC_2 R_2} \cdot \frac{1 + sC_2 R_2}{(1 + sT_1)(1 + sT_2^*)} \cdot \frac{R_1}{R_1 + R_2} A_0$$



LA BANDA DEL CIRCUITO COSÌ MODIFICATO RISULTA PARI A CIRCA 240 Hz -